

# Project 17

## Development of Next-Generation Seismic Design Value Maps

Provisions Update Committee  
Final Report

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# Project Goals

- Explore means of stabilizing fluctuating desing requirements triggered by periodic updates to the maps (yo-yo effect)
- Complete work on spectral shape adjustment initiated in prior cycle
- Deterministic ground motions following demise of the “characteristic earthquake magnitude”

# Acceptable risk

- The probability that ground motion at a building site will exceed levels that buildings will be designed to resist
- Presently- acceptable risk is defined as:  
“Less than a 10% notional probability that buildings will experience collapse, given  $MCE_R$  shaking”

# Acceptable Risk

- Acceptable risk is achieved by:
  1. Design requirements (System limits,  $R$ ,  $C_d$ ,  $\Omega_0$  coefficients, detailing) capable of providing 90% reliability given a target shaking level.
  2. Selecting an appropriate target shaking level –  $MCE_R$ 
    - Probabilistic seismic hazard analysis

# Why Motions Get Large Near Major Active Faults

PHSA in its simplest form:

$$\frac{1}{\text{Ground Motion (GM) Return Period}} = \frac{1}{\text{Earthquake Return Period}} \times (1 - \text{GM Percentile})$$

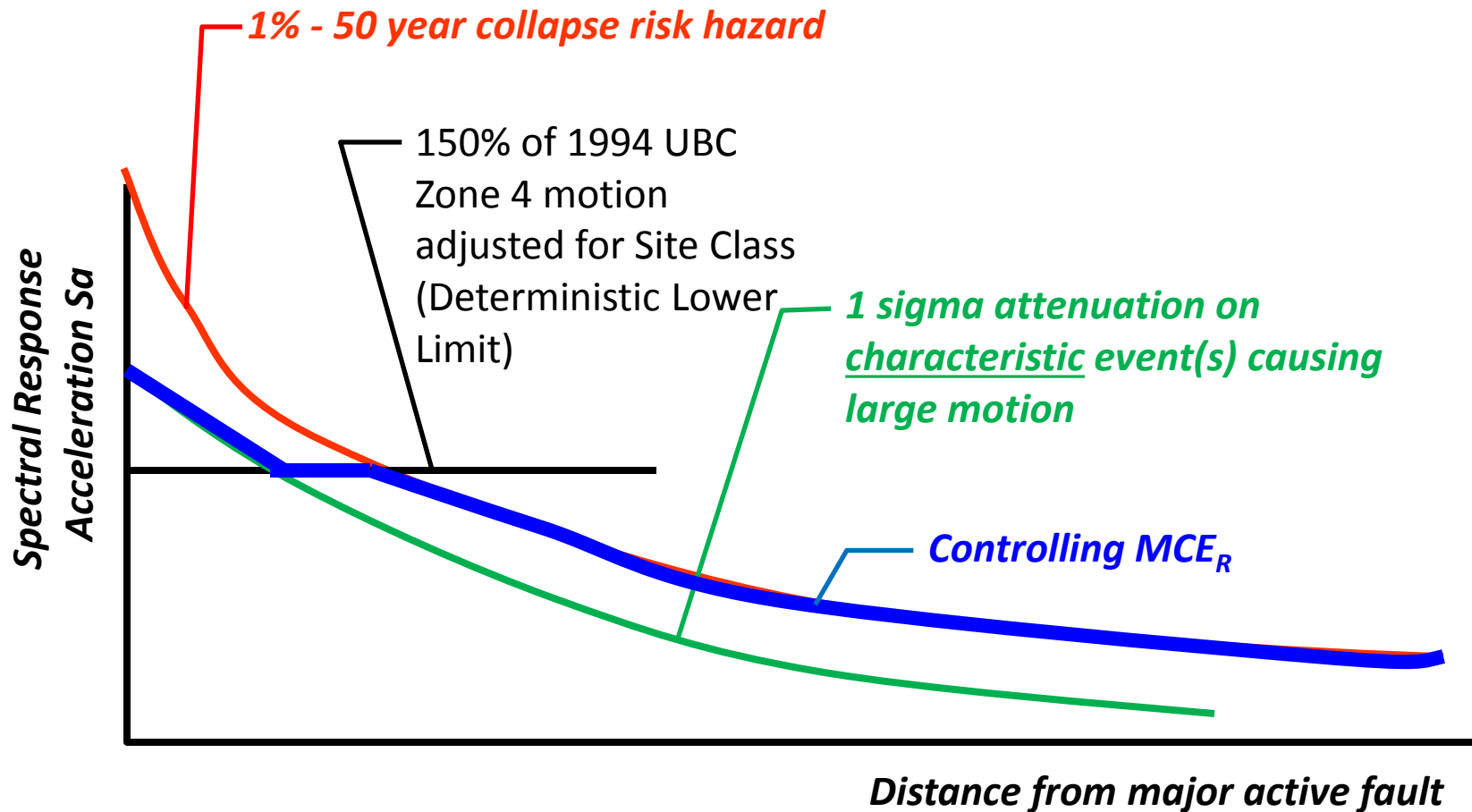
... e.g., for 2,500-year ground motions ...

$$\frac{1}{2,500 \text{ years}} = \frac{1}{1,200 \text{ years}} \times (1 - 56\%)$$

$$\frac{1}{2,500 \text{ years}} = \frac{1}{150 \text{ years}} \times (1 - 94\%)$$

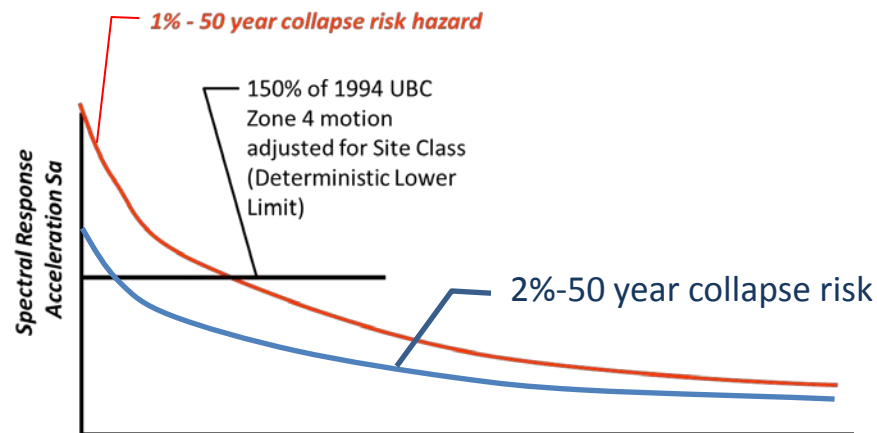
Because uncertainties in ground motion are high, high percentiles result in very large motions

# Target Chaking Level ( $MCE_R$ )



# Characteristic Earthquake

- UCERF 4 eliminated the concept of characteristic earthquake
  1. Reduce the return period for MCE shaking & eliminate need for deterministic limits



Results in increased risk nationwide

# Characteristic Earthquake

2. Retain current  $MCE_R$  but find alternative way to define deterministic limits
  - Select deterministic limit based on limiting “epsilon” (ground motion percentile) for faults contributing significantly to the earthquake hazard on strong shaking sites

# Proposal: Procedure at Each Location

1. Compute Risk-Targeted Ground Motion (**RTGM**).
2. If RTGM exceeds “Deterministic Lower Limit” (150% of 1994 UBC adjusted for site class)
  - At RTGM return period, **deaggregate hazard**.
  - From deaggregation, obtain **deterministic scenarios** that could result in RTGM (*i.e., fault/source names, magnitudes, distances, epsilons, relative likelihoods*).
  - **Adjust** each deterministic scenario to 84<sup>th</sup>-percentile ground motion by dividing RTGM by ...
    - $\exp(\text{Epsilon} \cdot \sigma) / \exp(1 \cdot \sigma)$
  - Use **largest** 84<sup>th</sup>-percentile ground motion amongst deterministic scenarios with relative likelihood  $\geq x\%$ .
  - Use lesser of deterministic motion, probabilistic motion, but not less than deterministic floor

Project ‘17 Deterministic Capping Subcommittee

# Example: San Bernardino, $S_{SRT} = 2.6g$

## Unified Hazard Tool

Please do not use this tool to obtain ground motion parameter values for the design code reference documents covered by the [U.S. Seismic Design Maps web tools](#) (e.g., the International Building Code and the ASCE 7 or 41 Standard). The values returned by the two applications are not identical.

### Earthquake Hazard and Probability Maps

#### Input

Edition

Dynamic: Conterminous U.S. 2014 (unknown)

Spectral Period

0.20 Second Spectral Acceleration

Latitude

Decimal degrees

34.1

Time Horizon

Return period in years

1901

Longitude

Decimal degrees, negative values for western longitudes

-117.3

2% in 50 years  
(2,475 years)

5% in 50 years  
(975 years)

10% in 50 years  
(475 years)

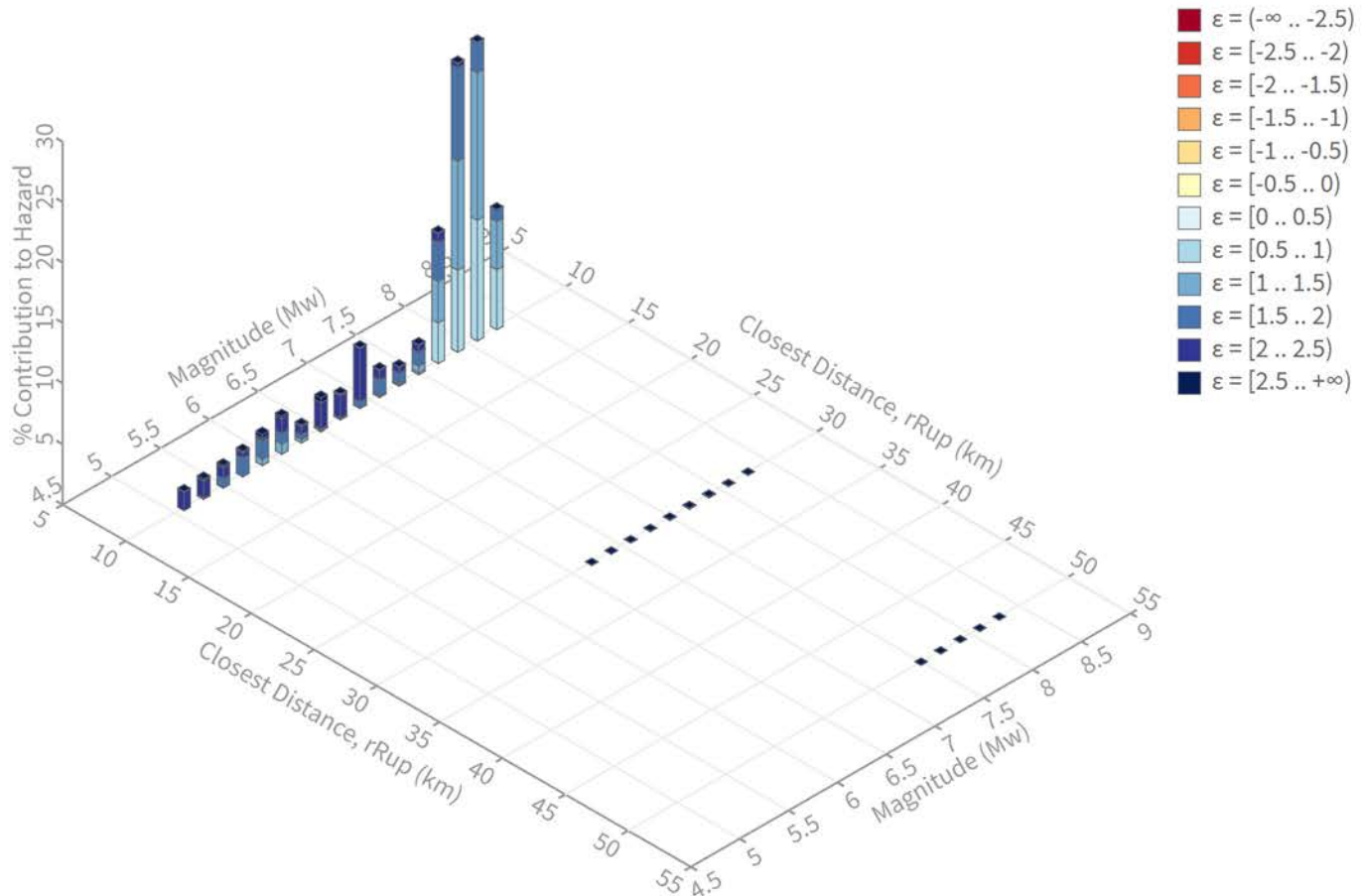
Choose location using a map

Site Class

760 m/s (B/C boundary)

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# Example: San Bernardino, $S_{SRT} = 2.6g$



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Example: San Bernardino,  $S_{SRT} = 2.6g$

*Deterministic scenarios that could result in 2.6g ...*

**Epsilon $\leq 1.0$   $S_s$**

2.4 g

**ASCE 7-16  $S_s$**   
 $= 2.3g$   
 (from  
 San Jacinto,  
 $M=7.7$ )

Source Name	Distance (km)	Magnitude	Epsilon	Relative Likelihood
San Jacinto	1.9	8.0	1.1	46%
San Andreas	8.4	7.6	1.7	34%
Capping the epsilons of these scenarios at 1.0 results in 84 <sup>th</sup> -percentile deterministic ground motions.				
Following the current <i>ASCE 7-16</i> deterministic capping procedure, use the largest 84 <sup>th</sup> percentile ground motion.				

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Following the current *ASCE 7-16* deterministic capping procedure, use the largest 84<sup>th</sup> percentile ground motion.

# YO-YO EFFECT



# Yo-Yo Effect

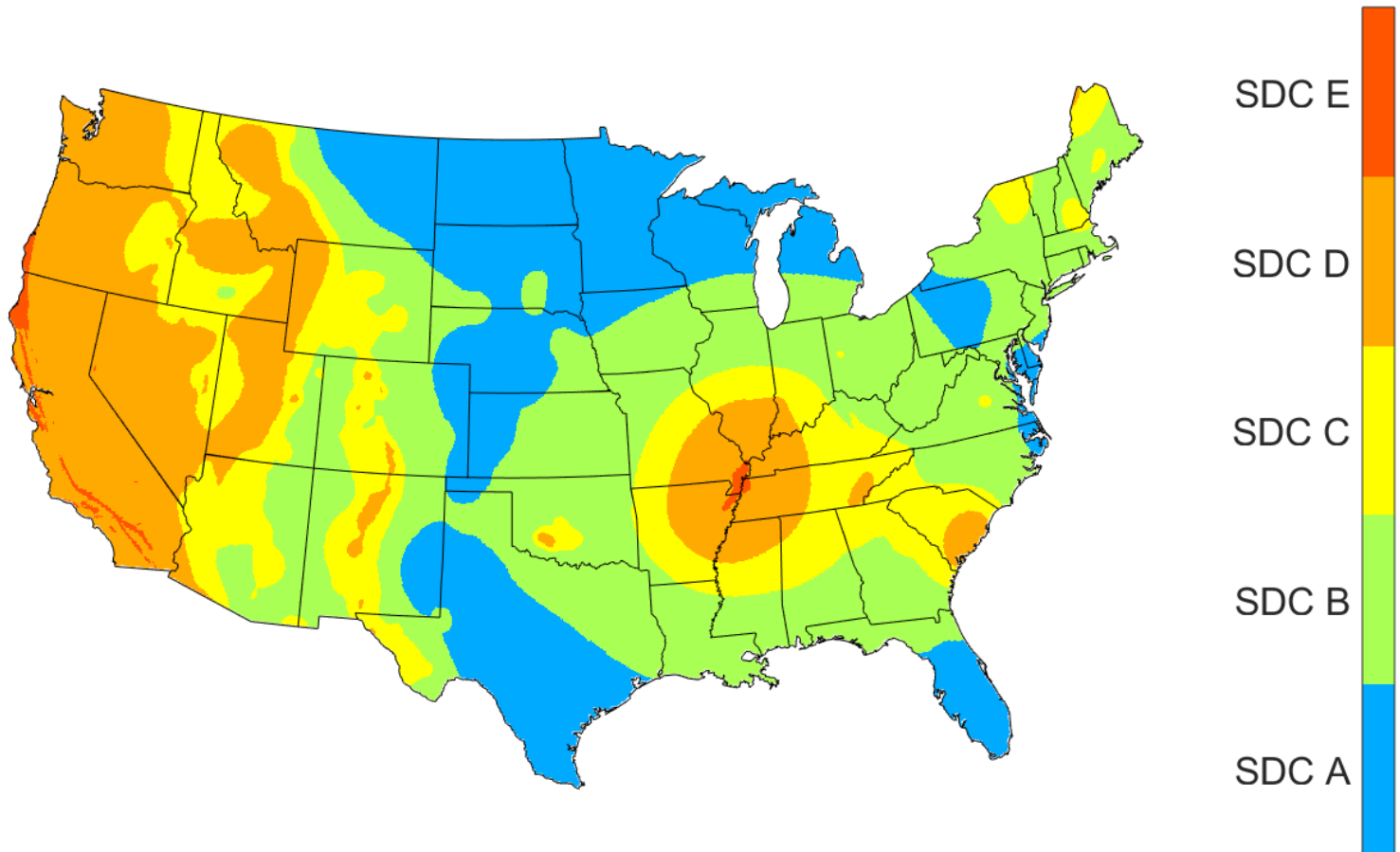
- Looked at ways of smoothing ground motion changes with code editions:
  - Reduce significant figures with which motions are reported (10% changes won't be noticeable)
  - Use weighted average approach to develop maps (50% new model, 25% past model, 25% earlier model)
- Minor (+/-15%) changes in ground motion values are annoying but not generally problematic
- Switches in SDCs are problematic

# Stabilizing SDCs

## Recommendation

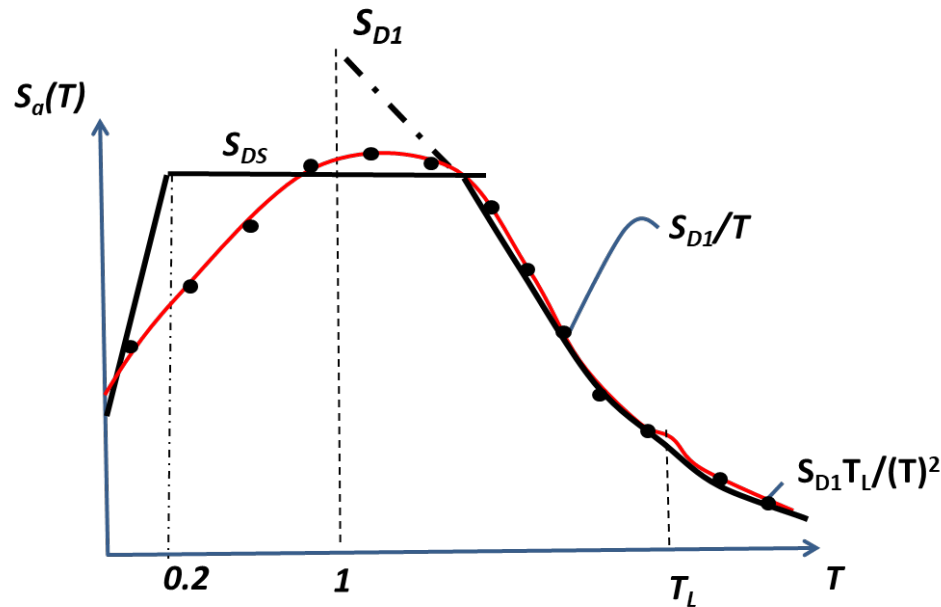
- Use separate SDC map to indicate designation of Design Categories
  - Map tied to ground motion values for a default site class
  - PUC uses judgement to move SDC boundaries or not, depending on reason for increase or decrease in motion and the magnitude of this
- Downsides:
  - Some structures designed too conservative
  - Lot of work for future PUC's

# SDC Map



# SPECTRAL SHAPE ADJUSTMENT

# Multi-point Spectrum



- Values provided at multi periods ranging from 0 to 10 seconds
- $F_a$  and  $F_v$  no longer used, site class used directly in hazard analysis
  - Somewhat finer gradation in site classes
- $S_{DS}$  taken as 90% of max spectral response
- $S_{D1}$  selected, so as to fit the spectral shape

# Summary

- Project 17 has passed recommendations to PUC for implementation
- Will develop final project report by September 30, 2018